Range-angle Decoupled Transmit Beamforming with Frequency Diverse Array

Xiang Zhe      Chen Baixiao

(National Laboratory of Radar Signal Processing, Xidian University, Xi’an 710071, China)

Abstract: It has been shown that Frequency Diverse Arrays (FDA) exhibit a range-angle dependent beam steering feature by employing a uniform frequency increment across the array elements. However, this beam pattern generates maxima at multiple range values, possibly leading to loss of signal-to-interference-plus-noise ratio when the interferences are located at any of the maxima. Herein, we prove that the beam pattern of FDA is range-periodic and propose the basic criteria for the FDA configuration to decouple the range and angle. In an illuminated space, a single-maximum beam pattern can be obtained by configuring the frequency increment between the elements. Specific examples have been discussed herein, and the simulation results verify the proposed theory.

Key words: Frequency Diverse Arrays (FDA); Range-angle-dependent; Single-maximum beampattern; Configuration

DOI: 10.12000/JR16113


1 Introduction

Frequency Diverse Arrays (FDA) radar has recently drawn much attention among the researchers. FDA differs from the traditional phased array by using a small frequency increment across the array elements, which results in a range-angle-dependent beam pattern. In FDA radar system is first proposed in Ref. [1]. In FDA radar, a uniform interelement frequency offset is applied across the array elements. FDA radar with uniform small and large frequency offset frequency has been investigated in Refs. [1–7]. Small frequency offset has been exploited to generate range-dependent beampattern, while large frequency offset can get independent echoes from the target.
Unlike the phased array, the range-angle dependency of the FDA beampattern allows the radar system to focus the transmit energy in a desired range-angle space. This unique feature of FDA helps to suppress the range-dependent interferences and increases the received SINR consequently. Especially for the mainlobe interference and clutter, the FDA can achieve a significant improvement in SINR against the phased array because the FDA provides the increased Degrees Of Freedom (DOFs) in range domain. However, the FDA beampattern is shown to be periodic in range and time, which goes to maximum at multiple time and range values. With this multiple-maximum beampattern, the resulting SINR will be deteriorated when the interferers are located at any of the maxima. To improve SINR, FDA with Time-Dependent Frequency Offset (TDFO-FDA) was proposed to achieve a time-independent beampattern at the target location. Nevertheless, the proposed beampattern is still periodic in range which will result in the loss of SINR. A nonuniformly spaced linear FDA with linear incremental frequency increment has also been studied in Ref. [10], and a nonrepeating beampattern has been obtained for range-angle imaging of targets. A uniformly spaced linear FDA with Logarithmically (Log-FDA) increasing frequency offset is proposed in Ref. [11]. The proposed strategy provides a nonperiodic beampattern with the single-maximum in space. In Ref. [12], the beampattern of FDA who transmits the pulsed signal has been studied. Lately, few more publications have done some work in decoupling the range-angle dependent beampattern of FDA. All these papers only address the properties of the FDA beampattern, and they do not study the common rule for the FDA configuration to form a single-maximum transmit beampattern.

With the pioneer work on FDA radar, we aim to decouple the range and angle in the beampattern and provide a nonperiodic beampattern with the single-maximum in the illuminated range-angle space. In this paper, we propose a basic criteria for the FDA configuration, in which the element spacing and frequency increment are configurable, to form a single-maximum beampattern through mathematical analysis. This single-maximum beampattern, unlike the multiple-maxima beampattern, can help to further suppress range-dependent interferences, causing improved SINR and increased detect ability. The proposed rule for the FDA configuration will be helpful to design the FDA.

The rest of the paper is organized as follows. In Section 2, the basic FDA model has been described and the basic criterion is derived for the FDA configuration to form a single-maximum beampattern through mathematical analysis. Moreover, several specific conditions are introduced. In Section 3, the beampattern has been plotted for the specific conditions discussed in Section 2. Finally, in Section 4 we conclude the paper.

2 Design and Mathematical Analysis of FDA

2.1 System description

Consider an array of $M$ transmit elements, we assume that the waveform radiated from each antenna element is identical with a frequency increment, as shown in Fig. 1. The radiated frequency from the $m$-th element is

$$f_m = f_0 + \Delta f_m, \quad m = 0, \ldots, M-1$$

where $\Delta f_0$ is the frequency increment of $m$-th element with reference to the carrier frequency $f_0$. Specifically, $\Delta f_0 = 0$.

Considering a given far-field point, the phase of the signal transmitted by the $m$-th element can be represented by

$$\psi_m = 2\pi f_m \left( t - \frac{r_m}{c} \right)$$

Fig. 1 FDA configuration
where c and \( r_m \) are the speed of light and the distance between the \( m \)-th element and the observed point, respectively.

The range difference between individual elements is approximated by

\[
\Delta r_m = r_0 - d_m \sin \theta_0
\]

where \( \theta_0 \) is the desired angle, \( d_m \) is the spacing between the \( m \)-th element and the first element. Specifically, \( d_0 = 0 \).

So the phase difference between the \( m \)-th element and the first element is

\[
\Delta \psi_m = \psi_m - \psi_0 = 2\pi \left( f_m \left( t - \frac{r_m}{c} \right) - f_0 \left( t - \frac{r_0}{c} \right) \right)
\]

\[
= 2\pi \Delta f_m t - 2\pi \frac{f_m d_m \sin \theta_0}{c} + 2\pi \frac{\Delta f_m r_0}{c}
\]

In Eq. (4), the third term is important because it shows that the FDA radiation pattern depends on both the range and the frequency increment. Taking the first element as the reference for the array, the steering vector can be expressed as

\[
a(\theta, r, t) = \left[ 1, \cdots, \exp \left( -j2\pi \frac{\Delta f_m (tc + r) + f_m d_m \sin \theta}{c} \right) \right]^T
\]

(5)

where \([\cdot]^T\) denotes the transpose operator.

In the pulsed-FDA, for \( t \in \left[ -\frac{T_e}{2}, \frac{T_e}{2} \right] \), \( T_e \) is the pulsewidth, the maximum value of phase variance\(^{[2]}\) during the pulse duration can be derived as

\[
\xi = \max_m 2\pi \Delta f_m T_e
\]

(6)

When the phase variance \( \xi \) is small enough, the beampattern of the pulsed-FDA can be viewed as quasi-static. Actually, in practical radar systems, duty cycle other than pulse duration is often used to describe the characterization of the pulsed-waveform. Then, the phase variance \( \xi \) can be further written as

\[
|\xi| = \max_m 2\pi \frac{\Delta f_m}{f_r} d_i = 2\pi d_i \max_m \rho_m \ll 1
\]

(7)

where \( d_i \) is the duty cycle, which is usually small. Eq. (7) holds when \( \max_m \rho_m \) is also small.

So under the condition Eq. (7), the time \( t \) can be neglected. So Eq. (5) can be simplified as

\[
a(\theta, r) = \left[ 1, \cdots, \exp \left( -j2\pi \frac{\Delta f_m r + f_m d_m \sin \theta}{c} \right) \right]^T
\]

(8)

2.2 Transmit beampattern analysis

Throughout this paper, we assume a narrowband system where the propagation delays manifest as phase shifts to the transmitted signals and Eq. (7) is satisfied. To steer the maximum at an expected target location \((\theta_0, r_0)\), the complex weights are configured as \(a(\theta_0, r_0)\), so the transmit beampattern can be expressed

\[
AF(\theta, r) = \left| a^H(\theta_0, r_0) a(\theta, r) \right|
\]

\[
= \sum_{m=0}^{M-1} \exp \left( 2\pi \frac{\Delta f_m (r-r_0) - f_m d_m (\sin \theta - \sin \theta_0)}{c} \right)
\]

(9)

where \([\cdot]^H\) denotes the conjugate transpose operator.

It is easy to see that the beam direction will vary as a function of the range and angle, which means the beampattern is range-angle dependent. Since the beampattern is coupled in the range and angle, the target’s range and angle cannot be estimated directly by the FDA beamformer output. Note that the beampattern is also related to \(\Delta f_m\) and \(d_m\), so the desired single-maximum beampattern can be obtained by setting the proper \(\Delta f_m\) and \(d_m\).

In Eq. (9), when \( m = 0 \), the exponential term is equal to 1. To obtain the maximum value of the beampattern, the exponential terms should be all equal to 1 for \( m = 1, 2, \cdots, M - 1 \). So the phase of the exponential term should be the integral multiple of \(2\pi\), which can be expressed as

\[
\Delta f_m (r-r_0) - f_0 d_m (\sin \theta - \sin \theta_0) = \frac{L_m c}{\Delta f_m} (\sin \theta - \sin \theta_0)
\]

(10)

where \( L_m \) is an integer, e.g. \( L_m = 0, \pm 1, \cdots, m = 1, 2, \cdots, M - 1 \).

The Eq. (10) can be rewritten as

\[
r = L_m c + f_0 d_m (\sin \theta - \sin \theta_0) + \frac{\Delta f_m}{\Delta f_m} (\sin \theta - \sin \theta_0) + r_0
\]

(11)

Since \( d_m (\sin \theta - \sin \theta_0) \ll r_0 \), the term \( d_m (\sin \theta - \sin \theta_0) \) in Eq. (8) can be neglected. The curves
formed by Eq. (11) will be called as range-angle distribution curves throughout the paper. Then Eq. (11) can be approximately expressed as
\[
\Delta f_m (r - r_0) - f_0 d_m (\sin \theta - \sin \theta_0) = L_m c, \ m = 1, 2, \cdots, M - 1
\]  
(12)

Rewrite Eq. (12) into matrix form as

\[
A \mathbf{x} = \mathbf{b}
\]  
(13)

where \( A = \begin{bmatrix} \Delta f_1 & -f_0 d_1 \\ \Delta f_2 & -f_0 d_2 \\ \vdots & \vdots \\ \Delta f_{M-1} & -f_0 d_{M-1} \end{bmatrix} \), \( \mathbf{x} = \begin{bmatrix} r - r_0 \\ \sin \theta - \sin \theta_0 \end{bmatrix} \), \( \mathbf{b} = \begin{bmatrix} L_1 c \\ L_2 c \\ \vdots \\ L_{M-1} c \end{bmatrix} \), \( L_m = 0, \pm 1, \cdots, m = 1, 2, \cdots, M - 1 \).

To decouple the range and angle, the beampattern should have the unique maximum point in the range-angle distribution diagram, which means the Eq. (13) has the unique solution \((\theta_0, r_0)\). The necessary and sufficient condition of that the Eq. (13) has the unique solution is

\[
\text{rank}(A) = \text{rank}(\tilde{A}) = 2
\]  
(14)

where \( \text{rank} (\cdot) \) is the rank of a matrix, \( \tilde{A} = (A, b) \).

When \( \text{rank}(A) = \text{rank}(\tilde{A}) = 1 \), the Eq. (13) has infinite solutions, corresponding to the conventional FDA condition, which will be discussed in detail later.

To satisfy \( \text{rank}(A) = 2 \), \( d_m \neq P \Delta f_m \), \( P \) is a constant.

To satisfy \( \text{rank}(A) = \text{rank}(\tilde{A}) \), \( L_m = Q d_m \) or \( L_m = S \Delta f_m \), \( L_m \) is an integer, and assume that \( Q, S \) are the minimum non-zero constants to satisfy the equations. Since \( d_m \neq P \Delta f_m \) must be satisfied, the two equations cannot be hold at the same time but when \( L_m = 0, \forall m = 1, 2, \cdots, M - 1 \).

In the following, under the condition of \( d_m \neq P \Delta f_m \), \( L_m = 0, \pm 1, \cdots \), we make a summary with different parameter configurations:

(1) when \( L_m = 0 \), the Eq. (13) has the unique solution \((\theta_0, r_0)\);

(2) when \( L_m = Q d_m \neq 0 \), \( L_m \neq S \Delta f_m \), the Eq. (10) has the solutions \((\arcsin (\sin (\theta_0) - k Q \lambda_0), r_0)\), \( \lambda_0 = \frac{c}{f_0} \), \( k = 0, \pm 1, \pm 2, \cdots \). When \( |\sin (\theta_0) - k Q \lambda_0| \leq 1 \), the angle grating lobes will occur at angle \( \arcsin (\sin (\theta_0) - k Q \lambda_0) \) in the beampattern. Otherwise, the Eq. (13) has no solution, resulting in no angle grating lobes;

(3) when \( L_m = S \Delta f_m \neq 0, L_m \neq Q d_m \), the Eq. (13) has the \((\theta_0, r_0 + S c k)\), \( k = 0, \pm 1, \pm 2, \cdots \), which means the range grating lobes will occur at \( r_0 + S c k \) in the beampattern.

Note that in array theory, when the adjacent element spacing is less than half the wavelength, the angle grating lobes will never appear. If \( Q \lambda_0 = \pm 1 \) and \( \theta_0 = 0^\circ \), where the element spacing is \( \lambda_0 \), then the grating lobes will occur at angle \( \pm 90^\circ \). But \( L_m = S \Delta f_m \) can always be satisfied since \( L_m \) is an integer whose range is \([-\infty, +\infty] \). The range grating lobes will always occur at range \( r_0 + S c k \) in the beampattern. The position of the range grating lobe changes with different \( S \). For example, \( S = 0.01 \), the distance between the grating lobe and the mainlobe is 3000 km. So if \( r_0 \pm S c \) is out of the illuminated range space \([R_{\text{min}}, R_{\text{max}}]\), the beampattern has a single-maximum point \((\theta_0, r_0)\) in the illuminated range space, which means the range and angle are decoupled.

So we can conclude that the beampattern of the FDA is always range-periodic, the grating lobes will always occur at range \( r_0 + S c k \), \( k = 0, \pm 1, \pm 2, \cdots \). To obtain the single-maximum beampattern in the illuminated range space \([R_{\text{min}}, R_{\text{max}}]\), the designing criteria for the FDA is \( d_m \neq P \Delta f_m \), and \( 2 S c > R_{\text{max}} - R_{\text{min}} \), \( |\sin (\theta_0) \pm Q \lambda_0| > 1 \), \( k = 0, \pm 1, \pm 2, \cdots \), \( L_m = 0, \pm 1, \cdots, m = 1, 2, \cdots, M - 1 \), \( P \) is a constant. \( Q, S \) are the minimum non-zero constants to satisfy the equations \( L_m = S \Delta f_m \neq 0 \) and \( L_m = Q d_m \neq 0 \).

Once the range and angle is decoupled, the target’s range and angle can be estimated directly by the FDA beamformer output. Also the 2-dimensional MUSIC algorithm[16] for estimating the target’s range and angle can be used as well.

### 2.3 Specific examples

For the conventional FDA, \( \Delta f_m = m \Delta f, \ d_m = md, \) \( \Delta f \) and \( d \) are configurable parameters to control the frequency increment and the element spacing. When \( L_m = n m \), \( n = 0, \pm 1, \pm 2, \cdots \),
m = 1, 2, ⋯, M – 1, we can get rank (A) = rank (A) = 1. Under this circumstance, the Eq. (13) has infinite solutions. The solutions form the range-angle dependent curves, which have expressions as:

\[ r = \frac{f_0 d}{\Delta f} \sin \theta - \frac{f_0 d \sin \theta_0}{\Delta f} + r_0 + \frac{n c}{\Delta f} \]  

(15)

In Eq. (15), the expression is no longer related to m, which means the range-angle curve for different element coincides with each other, as depicted in Fig. 2(a). In the range-angle distribution diagram, the curve is periodic in range, and the range difference between the adjacent curves is c/\(\Delta f\). The corresponding beampattern is depicted as Fig. 3(a).

For the Expf-FDA, whose frequency increment is exponentially increased, \(\Delta f_m = (b^m - 1) \Delta f\), \(d_m = md\). b is a configurable constant. The range solution rises when b gets larger. The range-angle distribution curves and beampattern are depicted in Fig. 2(b) and Fig. 3(b), respectively.

Likewise, for the Logd-FDA, whose element spacing is logarithmically increased, \(\Delta f_m = m \Delta f\), \(d_m = \log(m + 1) d\). When \(L_m = nm\), \(n = 0, \pm 1, \pm 2, \cdots, m = 1, 2, \cdots, M – 1\), we can get rank \((A) = \text{rank} (A) = 2\), so the range grating lobes will occur in the beampattern as depicted in Fig. 3(c), and the range difference between the grating lobe and the mainlobe is \(c/\Delta f\). The corresponding range-angle distribution diagram is depicted in Fig. 2(c).

For another kind of FDA, called Expf-Logd-FDA, where the frequency increment is exponentially increased and the element spacing is logarithmically increased, \(\Delta f_m = (b^m - 1) \Delta f\), \(d_m = \log(m + 1) d\). The range-angle distribution curves and beampattern are depicted in Fig. 2(d) and Fig. 3(d), respectively.

3 Simulations, Results, and Discussions

Bampattern expressed in Eq. (9) and the range-angle distribution curves expressed in Eq. (11) were simulated and plotted for different kinds of FDA discussed in Section 2. The results are discussed and compared with the different kinds of FDA. The illuminated range space is \((0 \text{ km, 800 km})\]. To generate these plots, the values of the configurable parameters have been taken as

![Fig. 2 The range-angle distribution diagram for different element](image-url)
listed in Tab. 1. To avoid angle grating lobes, the parameter \( d \) is less than half the wavelength.

\[
\frac{\Delta f}{f_m} = (1.4^n - 1) \Delta f, \quad \text{where} \quad \Delta f_m = \frac{c}{\Delta f} = 300 \text{ km}
\]

The range-angle distribution curves are depicted in Fig. 2. The curves with different color represent the range-angle distribution for different elements except the reference element in the FDA. It is easy to see that the range-angle distribution of the elements are the same in conventional FDA, and the range difference between the adjacent curves is \( c/\Delta f = 300 \text{ km} \), which is consistent with the analysis in Section 2. For the Expf-FDA and Expf-Logd-FDA, the beampatterns have a single-maximum point in the illuminated space corresponding to the single intersection point in the range-angle distribution diagram. For the Logd-FDA, the beampattern has 3 range grating lobes corresponding to the 3 intersection points in the range-angle distribution diagram. The beampatterns are depicted in Fig. 3. Similar to the range-angle curve in Fig. 2, the beampattern of the conventional FDA is a range-angle-dependent beampattern. For the Expf-FDA and Expf-Logd-FDA, the beampatterns have a single-maximum point in the illuminated space corresponding to the single intersection point in the range-angle distribution diagram. For the latter 3 FDAs, the contour of the beampattern is an ellipse, which is because the range-angle distribution curves are tightly distributed. The direction of the major axis of the ellipse is corresponding to the most tightness distribution direction of the range-angle distribution curves.

In the meanwhile, we analyze the range and angle solutions of different FDAs in Fig. 4. The Expf-FDA and the Expf-Logd-FDA have the same range solution, and the range solution of conventional FDA and Logd-FDA are the same. That is

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**Tab. 1 Parameters for simulations**

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Value</th>
<th>Parameter</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>Element number</td>
<td>( M ) = 8</td>
<td>( d )</td>
<td>0.1 m</td>
</tr>
<tr>
<td>Reference frequency</td>
<td>( f_0 ) = 1 GHz</td>
<td>( b )</td>
<td>1.4</td>
</tr>
<tr>
<td>( \Delta f )</td>
<td>1 kHz</td>
<td>Desired point</td>
<td>((\theta_0, r_0)) ((0^\circ, 400 \text{ km}))</td>
</tr>
</tbody>
</table>

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because the bandwidth across the whole array is the same for each pair. The same situation occurs for the angle solution, if the arrays have the same array aperture, they have the same angle solutions.

We choose the target position at (400 km, 20°), and the transmit beampattern is depicted in Fig. 5. Similar to Fig. 3, we can see that the single maximum beam is formed at the target position.

4 Conclusions

In this paper, we propose a basic criteria for the FDA configuration to provide a single-maximum beampattern in the illuminated space. The single-maximum beampattern can be generated by configuring the element spacing and frequency increment of the FDA. Through the analysis, we can find out that the beampattern of FDA is always range-periodic. Results show that a single-maximum beampattern can be generated with the corresponding criteria by choosing the proper frequency increment. As this paper describes the transmitter only, designing an appropriate receiver is our future work.
References


Xiang Zhe was born in Anhui, China in 1992. He received the Bachelor Degree in 2009 from Xidian University. He is currently working toward his Ph.D. degree in Signal Processing at National Laboratory for Radar Signal Processing of Xidian University. His major interests are frequency diverse radar, polarimetric radar, and interference suppression.

E-mail: xzysn152@163.com

Chen Baixiao was born in Anhui, China in 1966. He received the Master degree and the Ph.D. degree in 1994 and 1997, respectively, from Xidian University. He is a professor with National Laboratory for Radar Signal Processing of Xidian University. His research interests include array signal processing and polarimetric radar.

E-mail: bxchen@xidian.edu.cn